CAN Expansion Module V1

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| **Prepared By** | **Date** | **Checked By** | **Change History** |
| Raheel Farouk | 12JAN2023 | - | Initial Version |
| Raheel Farouk | 16JAN2023 | - | Added Endianness and Cleaned up formatting |
| Raheel Farouk | 06MAR2023 | - | Removed slip angle sensor and added Aux2 |
| Patrick Murphy | 09MAR2023 | - | Added Descriptions of data and Setup information |
| Patrick Murphy | 21APR2023 | - | Added Changes Relating to Library change, data frame update and connections. |

# Purpose of Module

The purpose of the CAN Expansion Module is to convert desired analog sensor inputs into digital data on the CAN bus.

# Setup Guide

Setting up the Expansion Module requires a CAN ID for the expansion module and the sensors to be plugged into their corresponding spots on the module. The MoTeC firmware will decide between what input will be used for each function, for example brake temperature will select the brake temperature input but you will be able to choose between front and rear, left and right.

## Board Configuration

The board is currently based on the Canduino V3.1, an atmega328P with an attached MCP2515 and MCP2551 to allow communication onto a CAN network. More information on this can be found in the following locations.

<https://www.tindie.com/products/massivegroup/canduino-v31-atmega328p-with-can-bus/>

<https://github.com/MassiveButDynamic/canduino-v3.1>

A custom PCB has been designed to support the desired functionality of 4 ADC pins with independent power and ground wires to reduce common failure points for each sensor.

<https://github.com/Panther-Racing/Expansion-Module-V1>

## Can Library Configuration

The library used to communicate with the MCP2515 as recommended by the Canduino is the Arduino-mcp2515 library. Previously the MCP\_CAN library by coryjfowler was used however issues were encountered relating to significant transmit errors on the bus so this is no longer used.

## Analog Sensor Wiring

|  |  |
| --- | --- |
| **Sensor Name** | **PIN** |
| Brake Temperature | ADC 0 |
| DPOS | ADC 1 |
| AUX 1 | ADC 2 |
| AUX 2 | ADC 3 |

# Module Specifications

The Canduino possess 8 ADCs, a 3v and 5v output, SPI interface and 10 Digital outputs. There is the option of having a CAN termination resistor through a solder bridge aswell as a chip select through a solder jumper.

# Messaging Structure

## SPI Message structure

|  |  |  |
| --- | --- | --- |
| **Endianness** | Big Endian | |
| **Message Length** | 8 | |
| **Byte** | **Contents\*** | |
| Byte0 | Brake Temp (9-2) | |
| Byte1 | Brake Temp (1-0) | DPOS (9-4) |
| Byte2 | DPOS (3-0) | Aux 1 (9-6) |
| Byte3 | Aux 1 (5-0) | Aux 2 (9-8) |
| Byte4 | Aux 2 (7-0) | |
| Byte5 | Firmware Version | |
| Byte6 | Transmit Error Counter (TEC) | |
| Byte7 | Counter | |

\*Note: The numbers in brackets are the bit numbers of the data stored in the byte. For example if Brake temp is a 10bit value, then the most significant first 8 bits of brake temp, Bits 9 to 2 will be stored in byte 1, then the remaining 2 bits will be stored in byte 1.

## Can Message Structure of Data

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Base CAN ID:** | 0x760 ; +1 ; +2 ; +3 | | | |
| **Data Name\*** | | **Length (Bits)** | **Position in Message** | |
| **Start** | **End** |
| Brake Temp | | 10 | 0 | 9 |
| DPOS | | 10 | 10 | 19 |
| Aux 1 | | 10 | 20 | 29 |
| Aux 2 | | 10 | 30 | 39 |
| Firmware Version | | 8 | 40 | 47 |
| Transmit Error Counter (TEC) | | 8 | 48 | 55 |
| Counter | | 4 | 56 | 59 |

\*Note: that the Data will effectively be sent as unsigned integers with values in the range of 0 to 2^(length of bits). Any conversion of this information currently needs to be performed on the receiving end of the data.

# Additional Notes

Auxiliary sensor attached to things like steering position.

## Description of Firmware Version

The firmware version corresponds to the current version of the Module. This is represented in format the format of vXX.X. In the software this is programmed as a uint8\_t type. To achieve the decimal position the firmware version must be 100 times the current version. For example if the current version of the module is v0.1 then the firmware version shall be 100\*0.1 or 100.

## Description of Compound

Compound is unimplemented. To be used if the length of data the module transmits exceeds 8 bytes of information to allow more data extraction from the same CAN ID.

## Description of Counter

Counter is a 4bit value used to determine if loss of transmission occurs. If observing transmission from the board this value shall go from 0 to 15 and rollover, if any value is missed while this is occurring then a loss of transmission has occurred and should be investigated.

## ADC

For the ATMEGA328 there are 6 ADC pins which are multiplexed to a single ADC. The ADC can use the internal voltage, a reference voltage, or 3.3V using the registers.

Transmit Error Counter (TEC)

The TEC is read from the mcp2515 registers using SPI. This describes the number of times that the controller has been broadcasting to the CAN bus but has detected that a value it sent was not properly sent.